

InertiaCube3 and Mounting Plate

# Precision Orientation Reference System

- Inertial-based tracking from integration of nine sensing elements
- Sourceless tracking with full 360° range
- 180 Hz update rate with adjustable motion prediction
- Adjustable output filters and rotational sensitivity
- SDK for OEM applications on Windows and Linux platforms
- Software libraries support up to 32 sensors simultaneously
- Windows software provides simple configuration, network interface and joystick emulation
- MagCal software for in-situ heading calibration
- OEM options for buttons, indicators, and analog controls

The InertiaCube3 is the world's smallest inertial orientation reference system. Providing full 360° sourceless tracking in all axes, the InertiaCube3 integrates nine discrete, miniature sensing elements with advanced Kalman filtering algorithms. Its simple serial or USB interface with support software provides a rapid development cycle for OEM applications. An available 1<sup>2</sup>C bus supports buttons, indicators, and analog controls for custom applications.

The low power consumption and wide temperature range of the InertiaCube3 make it ideal for head or body tracking in mobile simulation, training and situational awareness applications. Standard heading calibration software compensates for static magnetic field distortions when the InertiaCube3 is deployed in adverse environments. The InertiaCube3 is available with both wireless and dedicated processor options.

## InertiaCube3 Specifications

Degrees of Freedom **Angular Range Maximum Angular Rate\*** Minimum Angular Rate\* RMS Accuracy\* RMS Angular Resolution\*

**Serial Interface Update Rate Minimum Latency** Prediction

Serial Rate Interface Size (without mounting plate)

Weight **Cable Length** 

Power **Operating Temperature Range O/S Compatibility** 

**Software Support** 

3 (Yaw, Pitch and Roll) Full 360° - All Axes 1200° per second

0° per second

1° in yaw, 0.25° in pitch & roll at 25°C

0.03°

2 ms for RS-232 (PC host OS dependent)

up to 50 milliseconds 115.2 khaud

RS-232 Serial (shown above)

1.031 in x 1.544 in x 0.581 in (26.2 mm x 39.2 mm x 14.8 mm)

0.6 ounces (17.0 grams)

6 VDC, 40 ma 0° to 70° C

.dll for Windows Vista/XP/2000

.so for Linux

SDK with full InterSense API

**Ethernet via Windows Control Software** 

15 ft. (4.572 m) - Max. 75 ft (22.86 m)

**Heading Calibration Software** 

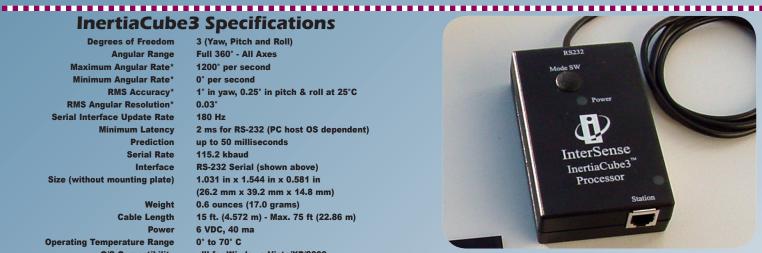
Measurements with perceptual enhancement algorithm turned off (= 0)

**Cable Length** 

### **Optional USB Adapter Specifications**

**InterSense USB Update Rate USB Interface Minimum Latency Power Source USB Adapter Size** 

2 ms for USB direct (Host & OS dependent) **Direct from Host USB Port** 2.36 in x 1.38 in x 0.79 in (60 mm x 35 mm x 20 mm) 6.4 feet (2 meters)



InertiaCube3 Processor

## **Optional InertiaCube3 Processor**

**Number of Trackers Supported Update Rate Supply Voltage Current Draw with one InertiaCube3 Current Draw with two InertiaCube3s Operating Temperature Storage Temperature** 

Sensor Interface **Host Interface** 

Size and Weight

up to two InertiaCube3 sensors 180 Hz nominal 6 VDC nominal 400 mA typical (320 - 550 mA) 440 mA typical (360 - 590 mA) 0° to +50° C -20° to +70° C, non-condensing two RS-232 Serial at 115.2 kbaud **Ethernet (TCP or UDP protocol)** RS-232 with only one sensor 6.0 x 10.0 x 2.5 cm and 86 grams

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